# Robot Playing Tic-Tac-Toe

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# Outline

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### Motivation

- Recently, population ageing phenomenon had become more serious and the population of **dementia** patients grows at the same time.
- Dementia patients will cause degeneration of brain memory, judgment, language functions disability.



#### Introduction

•The Tic-tac-toe robot is a interactive Robot, which can play the game with human.

•Use 4 Lego motors transmit the robot to draw cross and naught on the chessboard.

 Use a touch sensor for interaction and a webcam for catching image from the chessboard.



#### Tic-tac-toe Robot System Architecture



#### Self-made Motor Control Board



**12V power input** 

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#### Robot playing Tic-tac-teo

#### Self-made Motor Control Card - PWM



#### Software Flow Diagram



#### Image Processing



Chessboard image took by webcam



After image processing

Chessboard data

## Artificial Intelligent Game Algorithm

 $\mathbf{F} = F_{Attact} + F_{Defense}$ 

If robot plays the "X", player plays the "O" then

 $F_{Attact}$  = (the quantity of the **blank grid** in the horizontal, vertical, and diagonal row) x 1 + (the quantity of "X" in the horizontal, vertical, and diagonal row) x 2

 $F_{Defense} = 0$ , when there is **none** "O" in any the horizontal, vertical, and diagonal row.  $F_{Defense} = -1$ , when there is **one** "O" in any the horizontal, vertical, and diagonal row.  $F_{Defense} = 4$ , when there is **two** "O" in any the horizontal, vertical, and diagonal row.

The grid, which has the highest F, represented high priority and where the robot should play.

# Experiment Result



## Conclusions

- By using the SOC Linux environment, can reduce developing time of game algorithm and image processing.
- The sound function is also subjoined, which makes the game more fun.
- The Tic-tac-toe robot system can easily extend to four in a row or other interaction board game.

# Thanks for your attention

# Q&A